

Autonomous Switching of Self-Propelled Motion Modes of Hinokitiol-Fueled Elastomer Matrices

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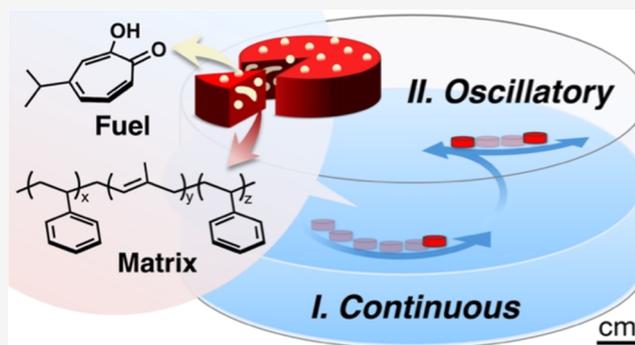


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ABSTRACT: Programmable self-propelled motion underpins essential biological functions and serves as a powerful inspiration in the design of dynamic synthetic materials. While significant progress has been made in developing self-propelled systems, most existing strategies rely on external stimuli or the incorporation of coupled oscillatory chemical reactions to achieve mode switching. In contrast, approaches that enable intrinsic switching between motion modes—such as from continuous to oscillatory—without external control remain limited. In this study, we introduce a self-propelled disk utilizing hinokitiol as a surface-active “fuel” within a polystyrene elastomer matrix, floating on the water surface. Hinokitiol-containing disks exhibited spontaneous transitions from continuous to oscillatory movement, distinctly without the need for external inputs. By leveraging the phase transitions of hinokitiol and tuning the mesoscale structure of the polymer scaffold, we succeeded in modulating the duration of continuous motion and frequency of oscillation in the macroscopic motion of the disks. These findings demonstrate that life-like macroscopic motion can be systematically engineered by coordinating the molecular arrangement of fuel species and the mesoscale structures of the surrounding polymer scaffold, presenting a versatile molecular design approach for synthetic self-propelled materials.



INTRODUCTION

Autonomous, periodic motion underlies a variety of sophisticated functionalities in living organisms, such as cardiac beat and peristaltic motion. Emulating such nonlinear behavior in synthetic systems remains a formidable challenge, but offers exciting opportunities for the development of new soft materials capable of self-sustained dynamic and adaptive responses.^{1–5} These advances could greatly benefit potential applications in soft robotics, medicine, and materials science.^{6–11} A number of synthetic systems have been reported to undergo self-propelled motion,^{12–29} typically exemplified by solid disks floating on water surfaces and oil droplets in aqueous solution, which are driven by the release of surface-active “fuel” molecules that generate interfacial surface tension gradients known as Marangoni flow.^{27,30–37} Some of these systems exhibit oscillatory motion by implementing inherently oscillatory reactions, such as enzymatic reaction cycles^{38–40} and the Belousov–Zhabotinsky reaction,^{41–44} or via chemical reactions that alter physicochemical parameters,^{45–48} such as surface tension, which govern self-propelled motion. Oscillatory motion is also known to occur in response to the environmental conditions around the self-propelled objects, such as the density of surfactants at the interface.^{49–55} In these aforementioned examples, the mode of motion remains unchanged unless environmental changes or additional species are deliberately introduced. Therefore, methods for inducing

transitions over time between different modes of motion—for instance from continuous to oscillatory motion—within a single system without external inputs have largely been overlooked.

There are a few examples of switching modes of motion in systems where Marangoni fuels are released from a scaffolding material, such as metal–organic framework (MOF) and agarose gel.^{56–61} These reports suggest the mode switching may arise from the modulated diffusion of the fuel through the scaffolding matrix. Although diffusion and release of small molecules from MOFs^{62–64} and various polymer matrices^{65–67} have been extensively studied, the potential for controlling mode switching behavior of self-propelled systems has not been explored. We envisioned that tunable macroscopic motion could be achieved by considering the polymer mesoscale structure in combination with the physicochemical properties of the chosen fuel species.

Here we present a simple system that demonstrates fully autonomous switching between continuous and oscillatory

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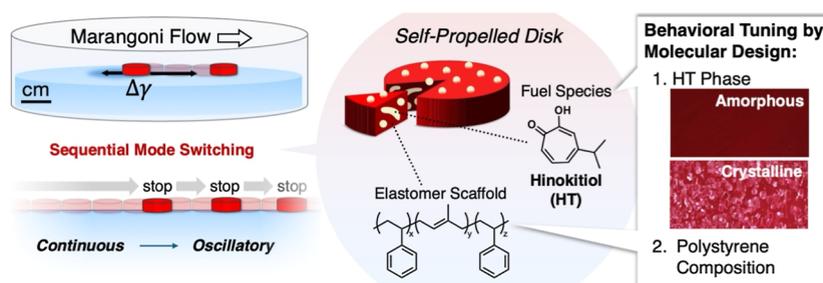


Figure 1. Chemical structures and schematic illustration of spontaneous switching from continuous to oscillatory motion caused by HT which can be tuned by adjusting the phase of HT and molecular composition of the disk scaffold.

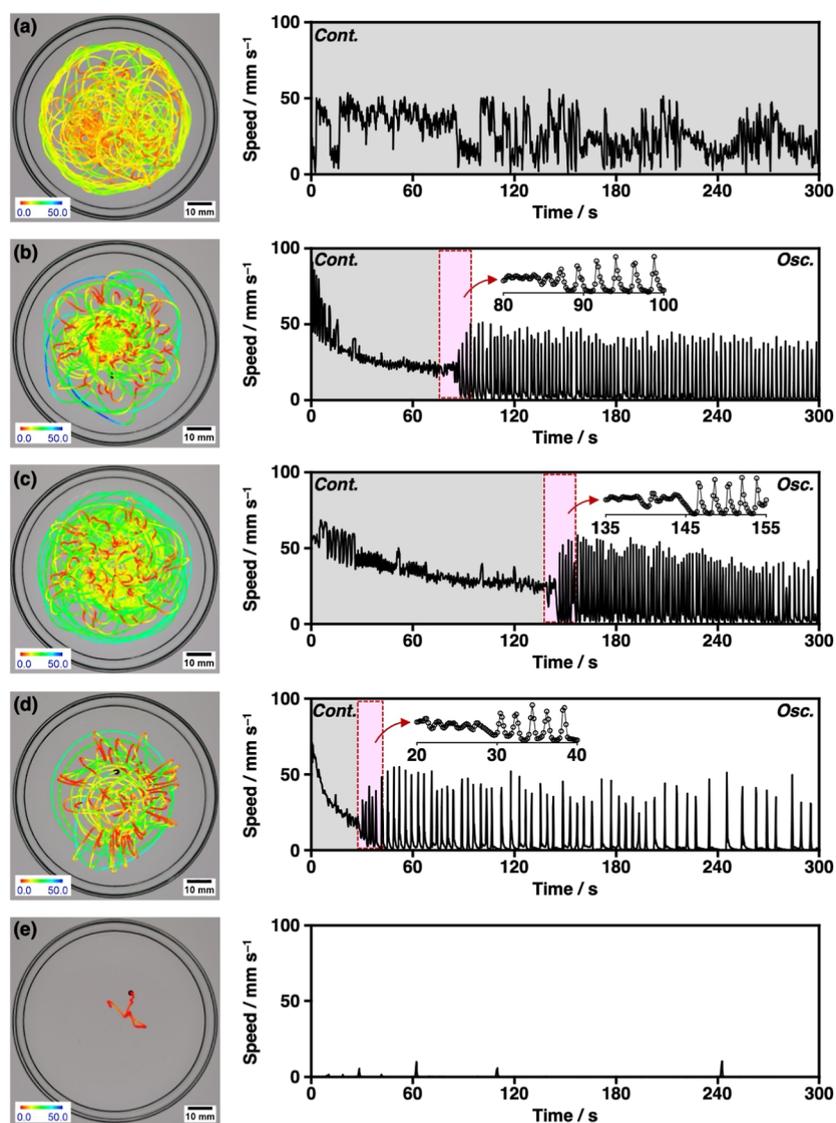


Figure 2. Motion fueled by HT. Trajectory and speed profiles of (a) a crystalline HT clump, (b) HT-SIS, (c) cHT-SIS, (d) HT-SIS50, and (e) HT-PS disks floated on distilled water at 25 °C. The gray regions indicate the continuous motion phase, while the white regions indicate the oscillatory motion phase. Enlarged views of the switching regions (red highlights) are shown in the insets.

modes of motion, achieved solely through the solid–liquid phase transition of a surface-active fuel and the phase-separated structures of the polymer matrix without any external inputs. We employed hinokitiol (HT) as the fuel species and polystyrene elastomer as the polymer scaffold (Figure 1). HT, a member of the tropolone family, is an aromatic compound with a seven-membered ring structure. Since its

isolation from the wood of *chamaecyparis taiwanensis* in the 1930s,⁶⁸ HT has garnered attention not only for its unusual structural chemistry,^{69–72} but also for its pharmacological activity in the fields of medicine and consumer products.^{73–76} Meanwhile, polystyrene elastomer is a widely used copolymer known to exhibit various phase-separated structures depending on its composition.⁷⁷ We found that, when placed on water,

disks composed of HT blended with an elastomer scaffold showed sequential mode switching from continuous to oscillatory mode without external input (Figure 1). Notably, the motility of the disk on the centimeter scale can be controlled by simply altering the disk fabrication procedure or by varying the composition of the polymer matrix. We systematically investigated the underlying mechanisms of this phenomenon using various fuel species and polymer matrices.

RESULTS AND DISCUSSION

Sequential Mode Switching of HT-Elastomer Disks.

When floated on distilled water at pH 7 under ambient conditions in a Petri dish, a small clump of HT crystals exhibited random, continuous motion consisting of large and small loops and twirling patterns (Figure 2a and Supporting Information Movie 1). The motion endured until the clump was spent, lasting up to ca. 2 h depending on the amount of sample. Such long-lasting behavior suggests HT does not accumulate on the surface of water, but rather is removed via dissolution into bulk solution. Although HT exhibits sublimation properties, its mass loss over 300 min is only about 7% (Figure S1), indicating that the contribution of sublimation to the overall removal process is minor. The self-propelled motion of the HT clump is comparable to that of the long-studied camphor,^{78,79} which is driven by the formation of a surface tension gradient that generates Marangoni flow.

A remarkable degree of sophistication emerged when disks were fabricated by combining HT with an elastomer. We prepared sheets of HT blended with an elastomer, polystyrene-polyisoprene-polystyrene triblock copolymer with 22 wt % styrene (SIS), in a 1:4 weight ratio which were subsequently cut into 2 mm diameter disks of 0.5 mm thickness, henceforth referred to as HT-SIS (see Supporting Information for the preparation methods). Initially, disks moved in rapid, continuous circles before transitioning via several small oscillations into an oscillatory mode characterized by periodic alternations between rest and rapid jumping which produced flower-like trajectory patterns (Figure 2b and Supporting Information Movie 2). Upon closer inspection of the HT-SIS disk, we observed that during the pauses in the oscillatory mode, the disk rotates in place (Supporting Information Movie 2, from 1:00 to 1:25). This rotation can rationally explain why the subsequent motion alternates back and forth rather than continuing in the same direction, as it perturbs the flow symmetry at the water surface. The duration of the continuous mode was on average 70 ± 10 s and the oscillatory motion continued for ca. 6.5 h, with a gradual decrease in frequency. The average speed of the rhythmic jumping was 40 ± 3 mm s⁻¹ with a frequency of 0.43 ± 0.09 s⁻¹ in the first 300 s. The friction coefficient of the disk on water can be calculated from the relaxation process during one jump cycle in the oscillatory mode. The frictional coefficient obtained from the first five jumps was determined to be $3.46 (\pm 0.13) \times 10^{-6}$ N m⁻¹ s (see Figure S2 for details), which is comparable to that of a plastic boat equipped with camphor.⁷⁹

To investigate the source of this mode switching, we allowed a fresh disk to swim for 300 s before relocating it to a second Petri dish with fresh water (Figure S3). The used disk immediately started oscillating, while a fresh disk added to the first Petri dish moved continuously before it started oscillating. Continuous to oscillatory type mode switching was still observed when the water depth was increased from 3 mm to 6 mm, and when the Petri dish diameter was changed from 75

mm to 50 mm, indicating the behavioral transition is not induced by the physical confines of the aqueous phase. When the surface of a SIS disk was coated with HT, only the continuous mode was consistently observed, and the duration of motion varied with the amount of HT; meanwhile, the oscillations became less frequent or disappeared entirely (Figure S4a and Supporting Information Movie 3). Disks constructed of just the SIS elastomer and the visualizing dye did not show self-propelled motion (Figure S4b and Supporting Information Movie 4). These results indicate that a layer of HT on the outer surface of the disk is responsible for the initial continuous mode, while HT inside the SIS elastomer disk may be responsible for the subsequent oscillatory mode.

Control of Motion Mode Using Phase Change of HT.

The phase-changing capability of HT provides an opportunity to alter its diffusion rate through the polymer scaffold. When a freshly prepared HT-SIS sheet was kept in a cold bath at -60 °C for 10 min and returned to ambient temperature, the elastomer sheet changed from opaque red to a dusty pink (Figure 3a). The cold-treated sheet, designated cHT-SIS, was

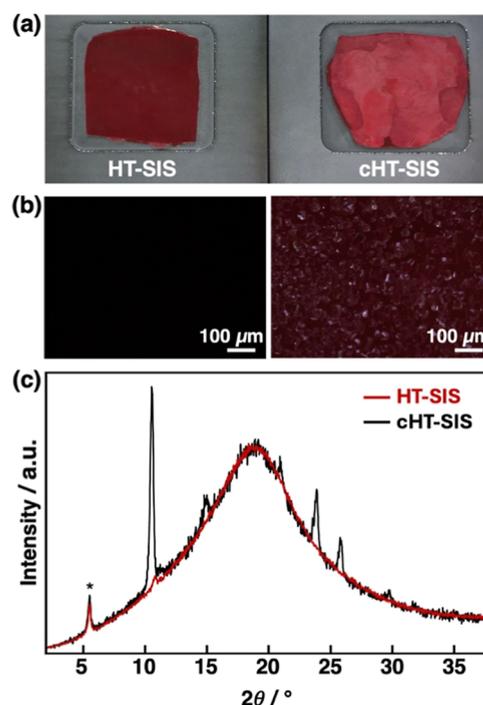


Figure 3. (a) Pictures of HT-SIS (left) and cHT-SIS (right) sheets. (b) Optical textures of HT-SIS (left) and cHT-SIS (right) observed under POM. (c) XRD patterns of HT-SIS (red line) and cHT-SIS (black line). The asterisk at $2\theta = 5.6^\circ$ (1.60 nm) denotes the peak corresponding to visualizing dye.

also markedly stiff in contrast to the soft, slightly sticky HT-SIS. When placed on water at 25 °C, cHT-SIS disks displayed a longer continuous mode and higher frequency oscillations than HT-SIS disks (Figure 2c and Supporting Information Movie 5). The average duration of the continuous mode for cHT-SIS increased to 151 ± 36 s and the frequency of the oscillatory mode was 0.59 ± 0.14 s⁻¹ with an average jump speed of 44 ± 8 mm s⁻¹. The self-propelled behaviors of HT disks with various compositions are summarized in Table 1.

To verify the tunability of the physical state of HT, we observed the melting of HT crystals to an isotropic oil at 52 °C. The sample remained in this liquid state long after it was

Table 1. Summary of the Self-Propelled Behavior of Different HT-Polymer Disks When Floated on Distilled Water Under Ambient Conditions^a

disk name	duration of continuous motion/s	frequency of oscillatory motion/s ⁻¹	speed of jumping/mm s ⁻¹
HT-SIS	70 ± 10	0.43 ± 0.09	40 ± 3
cHT-SIS	151 ± 36	0.59 ± 0.14	44 ± 8
HT-SIS50	45 ± 14	0.28 ± 0.09	32 ± 5
HT-PS		– (irregular)	8 ± 9

^aExperiments were conducted at least 6 times using fresh materials. The values were calculated for the first 300 s, along with their standard deviations.

cooled to 25 °C, demonstrating that HT can exist in both isotropic liquid and crystalline solid states at room temperature (Figure S5a). This supercooling phenomenon was also confirmed by differential scanning calorimetry (DSC) of pristine HT (Figure S5b). The elastomer itself may undergo a glass transition of its isoprene domain during the cold bath submersion, but otherwise did not show any changes within the temperature range of the sheet preparation conditions (Figure S5c). Observation under a polarized optical microscope (POM) revealed the surface of cHT-SIS was covered in polycrystals; no such optical textures were observed on the surface of HT-SIS (Figure 3b). As mentioned above, HT-SIS was molded by pressing at the melting point of HT, and cHT-SIS was prepared by subsequent cooling at –60 °C. Considering these preparation methods, the HT-SIS disk consists of fluid, amorphous HT, while the cHT-SIS disk primarily consists of crystalline counterparts. X-ray diffraction (XRD) measurements confirmed the increased crystallinity of cHT-SIS (Figure 3c). The peak pattern is consistent with the simulated XRD pattern from single crystal X-ray structural analysis of HT (Figure S6a). By contrast, the broad diffraction of HT-SIS indicates amorphous HT as the main component (Figure S6b). Thus, the duration time of the continuous motion and the frequency of the oscillating motion can be controlled by the amorphous and crystalline states of HT, as shown in Figure 2b,c.

To explain the causality between disk behavior and the crystallinity of HT, we considered how the latter affects the dissolution and supply from the disk onto the surface of the surrounding water. Time-dependent UV–vis absorption spectroscopy was employed to monitor the dissolution rate of HT from HT-SIS and cHT-SIS disks (Figure S7). A disk of either HT-SIS or cHT-SIS was placed on the surface of water in a cuvette, and the time profiles of the absorbance at 345 nm due to HT was monitored. The dissolution rate constant and final concentration of released HT were calculated by fitting to the Noyes–Whitney equation (see the Supporting Information for

details). The resulting values are summarized in Table S1. These results suggest HT deeper within the disk can more easily diffuse when in the amorphous state (HT-SIS).

As a consequence of the dampened supply of HT from its crystalline form, cHT-SIS showed a more pronounced change in behavior when placed on cold water compared to HT-SIS (Figure S8). Therefore, we floated the cHT-SIS disk on water at different temperatures and obtained the speed profile as shown in Figure 4. Initially, when the disk was floated on water at 25 °C, mode switching from continuous to oscillatory motion was observed at 98 s. When the disk was transferred to water at 5 °C, the frequency of oscillatory motion immediately decreased probably due to the slow diffusion of HT.⁸⁰ Upon returning the disk to water at 25 °C, both the frequency and speed of oscillatory jumping increased, approaching their original values. These observations indicate that cHT-SIS can switch its motion modes not only based on its own temperature history, but also in response to changes in the surrounding temperature.

Mechanism of Motion Mode Switching. The oscillatory mode of HT-SIS does not require coupling to a chemical reaction or additional surfactants. Such spontaneous transition of motion mode has been reported to show slight intermittent motion just before cessation when camphoric acid mixed with agarose gel is used.⁵⁸ However, the oscillatory motion of HT-SIS continued at a speed exceeding the average speed of continuous motion. Figure 5a illustrates the concentration profiles of HT released from the disk at different behavioral stages. We surmised the continuous mode arises from an initial layer of HT at the disk–water interface that is readily supplied to the local water surface. Note that the surface tension of aqueous solutions containing HT decreased linearly with increasing HT concentration before reaching a plateau, as shown in Figure S9. The supply rate of HT is high and its concentration asymmetry (ΔC) is maintained by the disk continuously relocating toward the region of high surface tension (Stage I). Over time, the amount of HT on the disk is consumed, resulting in a lower driving force. At this point, the supply rate is too low to counteract the combined effects of HT removal by dissolution and relocation, thus the disk abruptly slows to a halt (Stage II_a). In the oscillatory mode, the processes of supply and removal do not happen simultaneously. This may be due to interactions between HT and the hydrophobic disk surface which allow HT to accumulate around the base of the disk, generating a region of reduced surface tension (Stage II_b). Spontaneous symmetry breaking causes the disk to rapidly accelerate outside this region to an area of high surface tension (Stage II_c). The motion prevents sufficient accumulation of HT and the disk comes to a halt before repeating the cycle. The frequency of the oscillatory

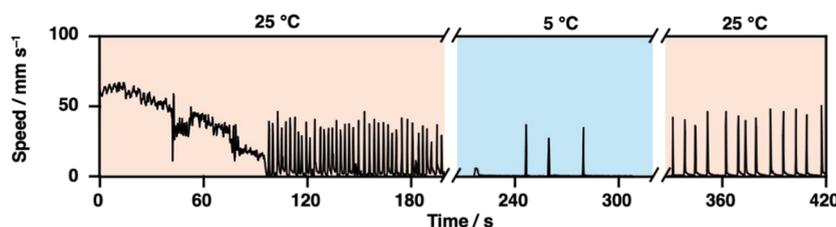


Figure 4. Speed profiles of cHT-SIS disks floated on distilled water at different temperatures. The time taken to transfer the disks to different Petri dishes is not shown.

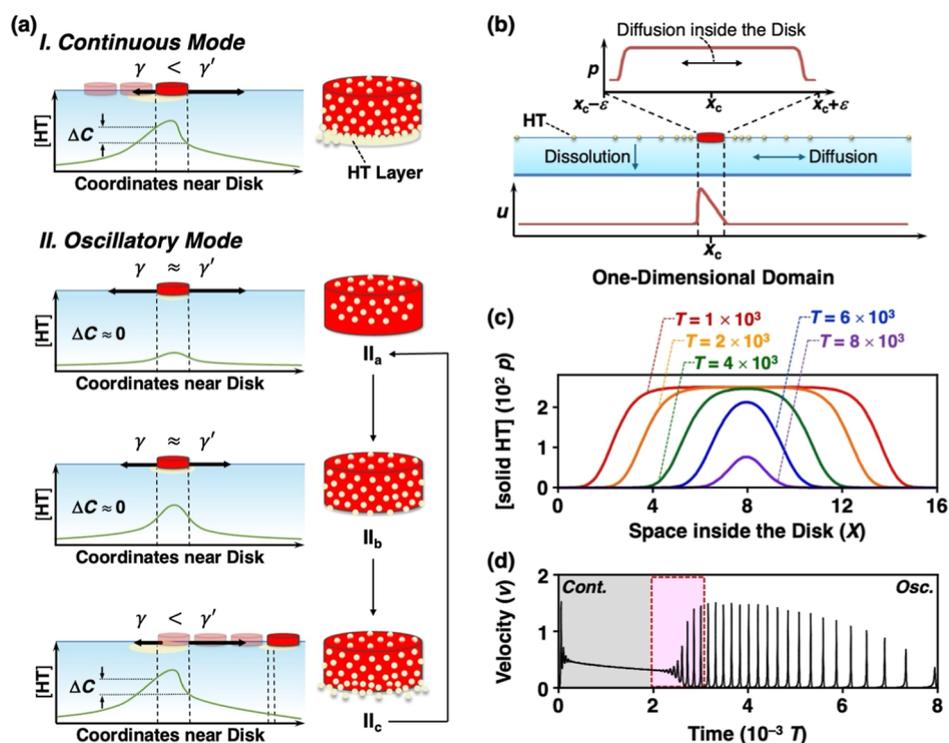


Figure 5. (a) Schematic illustration showing the plausible mechanism of sequential mode switching and the HT distribution in the HT-SIS disk. γ and γ' represent the surface tension at the back and front sides of the disk, respectively. (b) Schematic illustration of the setup of the mathematical model, where p , u , x_c , and ϵ represent the concentration of HT in the solid state, the surface concentration of HT, the position of the disk, and the radius of the disk, respectively. (c) Time evolution of the distribution of solid phase HT inside the disk. (d) Time series of the velocity of self-propelled motion. The gray, red, and white regions indicate continuous motion, transition, and oscillatory motion phases, respectively. Both results in (c) and (d) were obtained from numerical simulations.

mode decreases with time as the time it takes HT to diffuse from deeper within the matrix increases.

In order to verify the above mechanism, we performed numerical calculations of the self-propelled motion of the HT disk. The model was constructed on the basis of a previous report⁸¹ on the fundamental mechanism behind the self-propelled motion of a solid disk sliding on a water surface, which is driven by the surface tension gradient, while incorporating both the dissolution of HT from the disk surface and the diffusion of HT from the polymer matrix to the surface (Figure 5b; see the Mathematical Modeling section in Supporting Information for details). In this model, the HT concentration within the disk changes over time (Figure 5c). Initially, given that the disk was filled with a sufficient amount of HT, continuous motion was observed. Over time, HT at the edges of the disk was consumed, leaving depleted regions. As a result, the surface HT concentration decreased, leading to a gradual reduction in the disk speed for $T < 2 \times 10^3$, after which the mode of motion transitioned to oscillatory mode via several small oscillations. During oscillatory motion, the disk initially loses its driving force due to the depleted HT near the edges. However, HT molecules are readily supplied from the disk interior and diffuse along the bottom surface of the disk. When these molecules reach the edges, they regenerated the driving force, resulting in a burst of rapid motion. The subsequent rapid movement again lowers the surface HT concentration beneath the disk, causing the disk to stop. This cycle of velocity oscillations was reproduced in our simulations as shown in Figure 5d. Eventually, nearly all HT is consumed, and the disk comes to a complete stop. The simulated velocity

time series, which includes the transition from continuous motion to oscillatory motion, was in good agreement with our experimental results (Figure 2b–d and Supporting Information Movie 6).

To ascertain whether the mechanism of the motion mode switching is unique to HT-SIS, we conducted experiments by replacing HT with other self-propelling species. When tropolone—the parent compound of HT—was used, the SIS elastomer disk showed only a few seconds of continuous motion followed by one or two jumps before ceasing to move (Figure S10a and Supporting Information Movie 7). This result indicates the presence of the hydrophobic isopropyl moiety of HT is a crucial component for the sustained motion of HT-SIS. Substitution with camphor resulted in subtle rhythmic variations in speed, but none of the distinctive jumping motions occurred during the period of observation (Figure S10b and Supporting Information Movie 8). When camphoric acid was used, the SIS elastomer disk showed mode switching from continuous to oscillatory motion, however the behavior was less consistent and slower than HT-SIS. On average, the continuous mode lasted 11 ± 8 s and the average speed of the rhythmic jumping was 16 ± 15 mm s⁻¹ with a frequency of 0.16 ± 0.14 s⁻¹ in the first 300 s (Figure S10c and Supporting Information Movie 9). These results indicate there are properties of HT that make it particularly suited to inducing frequent, high-speed jumping motions after spontaneous transition from continuous motion mode when blended with the SIS elastomer scaffold.

We also measured the surface tension of these surfactants, or fuel species, because it is a crucial parameter that induces

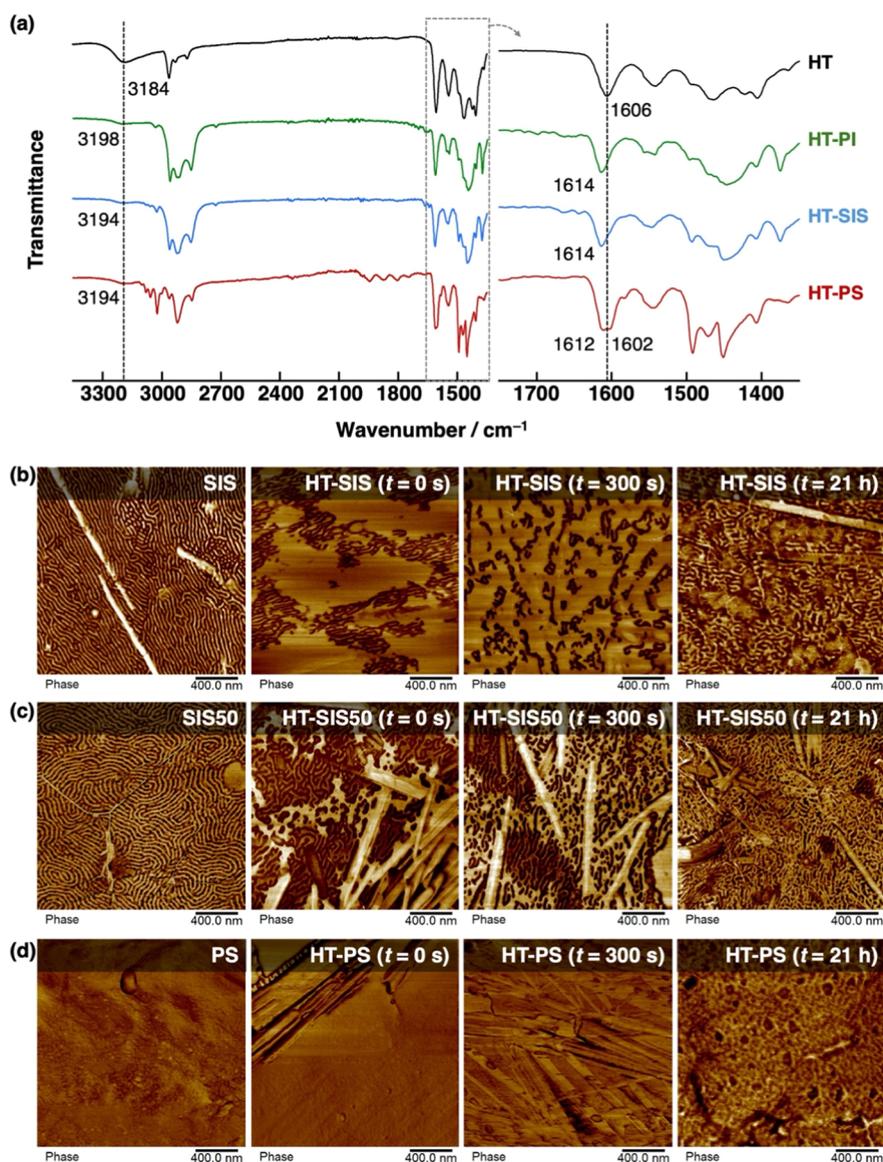


Figure 6. (a) FT-IR spectra of HT (black) and HT blended with either PI (green), SIS (blue), or PS (red). AFM phase images of (b) HT-SIS, (c) HT-SIS50, and (d) HT-PS disks before (center left) and after swimming for 300 s (center right) and 21 h (right) on distilled water at 25 °C. Each respective elastomer in the absence of HT is shown on the left. All samples contain 0.5 wt % visualizing dye.

Marangoni flow.⁷⁹ As mentioned above, the surface tension of aqueous solutions containing HT decreased before reaching a plateau, as shown in Figure S9a. By linearly approximating the change in surface tension in the low-concentration region, $\gamma = \gamma_0 - \alpha[\text{HT}]$, the α value for HT was obtained to be $4.8 \text{ N m}^{-1} \text{ M}^{-1}$. Similarly, the α values for tropolone, camphor, and camphoric acid were calculated as $0.07 \text{ N m}^{-1} \text{ M}^{-1}$, $5.0 \text{ N m}^{-1} \text{ M}^{-1}$, and $4.3 \text{ N m}^{-1} \text{ M}^{-1}$, respectively. With the exception of tropolone, the surface tension of these fuel species shows similar concentration dependence, implying that the concentration of HT in the aqueous surface layer must vary differently with time compared to the other species. To verify the role of ambient surface tension, we placed HT-SIS disks onto aqueous solutions containing sodium dodecyl sulfate (SDS), a typical surfactant previously used to induce oscillatory motion.⁵⁰ Low concentrations were chosen in order to approximately mimic the local surface tension surrounding the disk at different HT concentrations (Figure S9b), though it should be noted that SDS has a greater propensity to remain on the surface

compared to HT. At [SDS] of 0.5 mM the HT-SIS disk moved continuously for only a few seconds before jumping at irregular intervals (Figure S11a). At [SDS] of 1.0 mM and 2.0 mM, disks moved extremely slowly for more than 150 s before oscillating at frequencies of 0.04 s^{-1} and 0.03 s^{-1} , respectively (Figure S11b,c). These frequencies are more than 10-fold smaller than that of disks in the absence of SDS, which suggests it takes longer for a sufficient driving force to emerge when the ambient surface tension is lowered. Remarkably, the behaviors exhibited in Figure S11 can all be considered spontaneous mode switching, which demonstrates the emergence of the oscillatory mode is not caused by reaching some ambient surface tension threshold, in contrast to an earlier report using camphoric acid in agarose gel.⁵⁸ This implies the switch to rhythmic jumping behavior may be from temporal variations of [HT] as it is released.

To visualize how HT behaves on the surface as it leaves the disk, Quinizarin Green SS—a hydrophobic dye—was spread on the water surface before a HT-SIS disk was deposited. As HT

emerges from the disk into the surface layer of water, it lowers the surface tension causing the dye particles to be pulled away. During the continuous mode, a small clear area was observed trailing the disk (Figure S12a). The size of this diffusion layer remained constant, indicating the supply rate of HT to the surface is roughly equivalent to its removal rate from the surface. Figure S12b depicts one cycle of the oscillatory mode. The supply of HT to the surface is paused during the rest state as indicated by the absence of an expanding diffusion layer surrounding the disk. In a fraction of a second, a cleared region forms on one side of the disk before it rapidly accelerates. As the disk begins to slow to rest again, the trailing diffusion layer shrinks or is left behind. The oscillation of local HT concentration—and therefore, surface tension—with respect to time may be explained by considering the balance between the amount of HT supplied from the SIS elastomer and the rate of surface diffusion and dissolution (removal).⁵⁶

Control of Motion Mode Using Different Polymer Matrices. The rate at which HT is supplied from within the polymer matrix to the surface—consequently affecting the oscillatory behavior—should be influenced by not only the phase states of HT (amorphous versus crystalline), but also the components of the polymer matrix.^{82,83} Therefore, we studied how the motion mode of HT disk is affected by the phase-separated structure of the polymer matrix. We systematically prepared HT disks with varying polystyrene content: a disk with 22 wt % polystyrene as described above (HT-SIS), a disk with 50 wt % polystyrene (HT-SIS50), and a polystyrene-only disk (HT-PS). HT-SIS50 was prepared by blending high molecular weight polystyrene with the SIS elastomer to achieve 50 wt % styrene content (see Supporting Information for details).⁸⁴ As the styrene content of the disks increased, the self-propelled behavior became less intense. HT-SIS50 disks first displayed continuous motion for 45 ± 14 s on average, then oscillatory behavior between rest and sudden jumps that averaged 32 ± 5 mm s⁻¹ with a frequency of 0.28 ± 0.09 s⁻¹ during the first 300 s (Figure 2d, Table 1 and Supporting Information Movie 10). Meanwhile, HT-PS disks moved very slowly, showing no obvious continuous mode and irregular jumping motions that averaged 8 ± 9 mm s⁻¹ during the first 300 s (Figure 2e, Table 1 and Supporting Information Movie 11).

Fourier transform infrared spectroscopy (FT-IR) exhibited shifts in the carbonyl and hydroxyl stretching frequencies when HT was mixed with various polymer matrices (Figure 6a), indicating interactions between HT and the polymer matrices analyzed. When blended with either SIS or polyisoprene (PI), the characteristic carbonyl stretching of HT shifted from 1606 cm⁻¹ to 1614 cm⁻¹. Peak splitting to 1612 cm⁻¹ and 1602 cm⁻¹ was observed when blended with polystyrene (PS). The hydroxyl stretching frequency shifted from 3184 cm⁻¹ to 3198 cm⁻¹ when blended with PI and 3194 cm⁻¹ when blended with SIS or PS. These results indicate HT is distributed across both PI and PS domains. The substitution of tropolone blended with various polymers resulted in similar shifting and splitting of the carbonyl peaks, though no shift in frequency was observed for the hydroxyl stretching peak (Figure S13a). Camphor and camphoric acid also showed subtle shifting of their respective carbonyl peaks when blended with SIS (Figure S13b,c).

The surface morphology of disks with varying styrene-isoprene ratios was observed using atomic force microscopy (AFM) operated in tapping mode. Phase images, rather than

height images (Figure S14), were used to identify regions of differing stiffness and adhesion. The height and phase images of HT-SIS revealed large, relatively bright areas interspersed with worm-like dark domains (Figures 6b and S14a). After the disk was allowed to swim on distilled water for ca. 300 s the worm-like domains became more dispersed; after 21 h the worm-like domains became more densely packed and with average thicknesses similar to the bright regions of SIS in the absence of HT, albeit without its orderly lamellar structures. Notably, analogous disks constructed of other fuel species mixed with SIS did not show such drastic changes in morphology due to swelling of one domain when compared to SIS (Figure S14). This may be due to the ability of HT to remain in the liquid state after disk fabrication while the other fuel species do not. With the increased styrene ratio of the polymer matrix, the bright lamellae grew longer and thicker in SIS50; when blended as HT-SIS50, these lamellae were replaced by collections of highly complex morphologies (Figure 6c). Similar to the case of HT-SIS, the morphology of HT-SIS50 after 21 h appeared as densely packed, bright worm-like structures instead of the orderly lamellae of the SIS50 matrix. This suggests HT can affect the interfacial properties of PI and PS domains. No microphase separation was observed in HT-PS, which was in agreement with the FT-IR results suggesting miscibility between HT and polystyrene (Figure 6d).

Force curves were also measured to confirm the molecular composition and to characterize the mechanical properties of the bright and dark domains in each phase image (Figure S15).^{85–87} The bright regions recorded on a fresh HT-SIS disk showed a strong adhesive force and significant hysteresis compared to the dark worm-like regions (Figure S15a). After swimming for 300 s the adhesive force of the bright region appeared to weaken while the sample remained compliant, which may be attributed to the consumption of HT. Force curves measured on HT-SIS50 and HT-PS also showed changes in their stiffness and adhesive properties consistent with the release of HT after swimming (Figure S15b,c). The decrease in adhesive force and plastic deformation reflects several mechanistic implications. Initially, the local concentration of HT is high at the disk–water interface compared to the ambient water, causing a substantial decrease in local surface tension. Over the course of swimming, the amount of HT at the interface decreases causing the local surface tension to increase, which was confirmed by changes in water contact angles on the HT-SIS surface at various time intervals compared to that of SIS (Figure S16). The average value for fresh HT-SIS at $98.9 \pm 4.3^\circ$ was larger than that of SIS at $82.0 \pm 0.6^\circ$ which shows how the presence of HT weakens the interfacial tension between the disk and water relative to the surface tension of the water. After swimming on distilled water for 60 s, 300 s, or 17 h, the contact angles progressively decreased to $97.6 \pm 1.6^\circ$, $94.2 \pm 1.3^\circ$, and $84.5 \pm 0.7^\circ$, respectively. Consequently, the surface tension gradient, $\Delta\gamma$, surrounding the disk becomes smaller and the disk speed decreases.

In the oscillatory mode, the disk cycles between states of rest as HT builds up and rapid escape; therefore, the scaffold material can be used to modulate this buildup step based on how well it permits HT to diffuse from deeper within.⁸⁸ Although HT was found to be miscible with both blocks, the greatest morphological and mechanical changes were observed in the bright domain of HT-SIS, when the isoprene content

was highest, implying a preferential release pathway through domains constructed from the more flexible material. Conversely, the presence of interpenetrating PS domains may suppress the supply rate of HT. At 22 wt % styrene, the HT-swollen PI domain forms a large, continuous network that initially covers 79.8% of the field of view in Figure 6b, as analyzed using ImageJ (see Supporting Information for details). After swimming for 300 s, that surface coverage shrunk to 74.5% but maintained its connectivity, thus permitting multiple release pathways for rapid HT buildup during the oscillatory mode of HT-SIS. In the case of HT-SIS50, the surface area of the PI domain was reduced to ca. 50% of the field of view in Figure 6c. The patches where globular bright areas transition into less bright, worm-like structures imply that HT may not be consistently distributed in each polymer block, further limiting potential release pathways. This diminished surface coverage suggests the shorter continuous mode observed for HT-SIS50 may be attributed to a smaller initial HT layer compared to HT-SIS. After swimming for 300 s, the surface coverage of the soft domains decreased to ca. 35% while becoming more dispersed. As a result of fewer release pathways available, HT-SIS50 required longer HT buildup times resulting in lower-frequency oscillations. The amount of HT fuel accumulated in each cycle from HT-SIS50 may also have been diminished, which would account for slower average jump speeds compared to HT-SIS. The molecular size of the polymer chains themselves may also play a decisive role. In the case of HT-SIS, the relatively short styrene blocks have fewer opportunities to entangle, which may allow HT to easily permeate both domains. By contrast, the large chain lengths used to construct rigid HT-PS disks can more effectively constrain HT within the scaffold. When both types are combined, as in the case of HT-SIS50, the surface became more rigid after swimming which may hinder the continued diffusion of HT. Thus, the release of fuel species may be engineered via scaffold matrix design.

CONCLUSION

To conclude, we demonstrated here, for the first time, that HT exhibited self-propelled motion on water, and transition of motion modes—from continuous to oscillatory—when mixed with polystyrene elastomer matrices, even in the absence of any external input. By exploiting the unique property of HT, which can exist either as an amorphous oil or as a crystalline solid at room temperature depending on its thermal history, we were able to modulate both the duration of the continuous motion and the frequency of the oscillatory motion. Furthermore, blending the polystyrene elastomer with high molecular weight polystyrene enabled us to further regulate the diffusion rate of HT through the polymer matrix, which consequently affecting the oscillatory behavior. Our results underline that sophisticated self-propelled behaviors can be rationally designed by considering not only the molecular arrangement of the fuel species but also its interaction with the surrounding polymer scaffold. These insights present a novel strategy for the molecular-level design and control of macroscopic self-propelled behaviors, providing new perspectives for the development of synthetic life-like materials based on the interplay of fuel diffusion, phase transitions, and polymer microstructure.

ASSOCIATED CONTENT

Supporting Information

The Supporting Information is available free of charge at <https://pubs.acs.org/doi/10.1021/jacs.5c17346>.

Detailed experimental methods, Supporting Information, and additional references (PDF)

Movie S1. Motion of a clump of HT crystals when floated on distilled water at 25 °C (MP4)

Movie S2. Motion of a HT-SIS disk when floated on distilled water at 25 °C (MP4)

Movie S3. Behavior of a SIS disk coated with HT when floated on distilled water at 25 °C (MP4)

Movie S4. Behavior of a SIS disk containing no active species when floated on distilled water at 25 °C (MP4)

Movie S5. Motion of a cHT-SIS disk when floated on distilled water at 25 °C (MP4)

Movie S6. Simulation of the time evolution showing (left) the surface concentration of HT (u) as a function of the disk position (x) and (right) the distribution of solid phase HT inside the disk (p vs X) (MP4)

Movie S7. Motion of a tropolone-SIS disk when floated on distilled water at 25 °C (MP4)

Movie S8. Motion of a camphor-SIS disk when floated on distilled water at 25 °C (MP4)

Movie S9. Motion of a camphoric acid-SIS disk when floated on distilled water at 25 °C (MP4)

Movie S10. Motion of a HT-SIS50 disk when floated on distilled water at 25 °C (MP4)

Movie S11. Motion of a HT-PS disk when floated on distilled water at 25 °C (MP4)

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Notes

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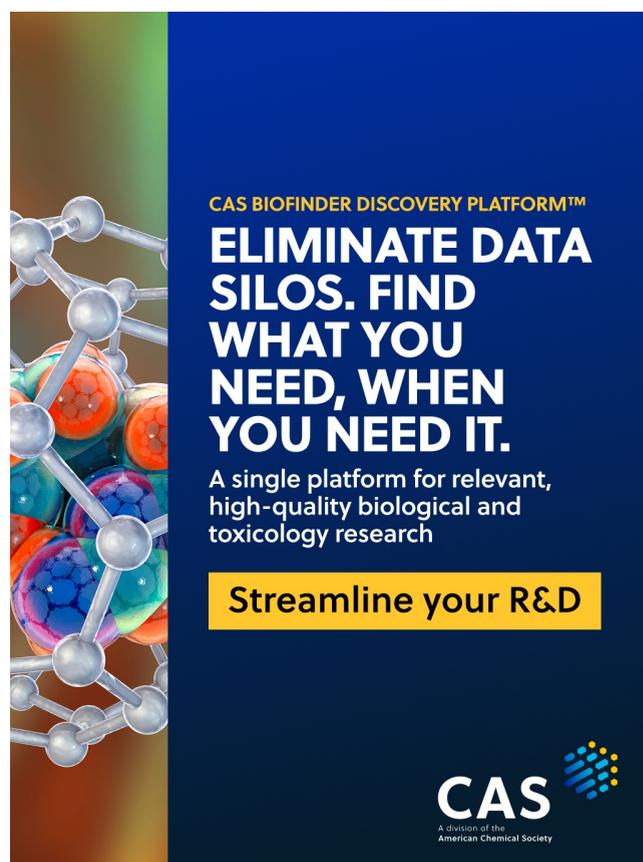
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